

Masking against Side-Channel Attacks: a Formal Security Proof

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Joint work with Emmanuel Prouff

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Outline

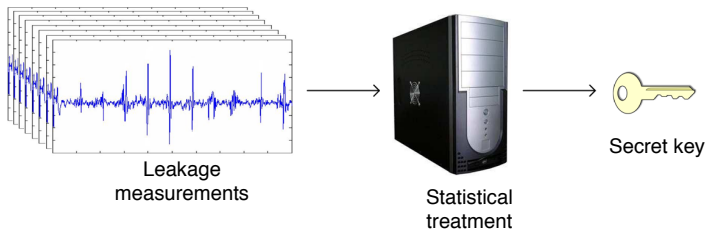
- 1 ■ Introduction and Previous Works
- 2 ■ Our Contribution
- 3 ■ Model of Leaking Computation
- 4 ■ Overview of the Proof
- 5 ■ Conclusion and Perspectives

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Side-Channel Attacks

- Attacks exploiting physical information leakage
 - ▶ timing [Kocher. CRYPTO'96]
 - ▶ power consumption [Kocher et al. CRYPTO'99]
 - ▶ electromagnetic emanations [Gandolfi et al. CHES'01]



Masking

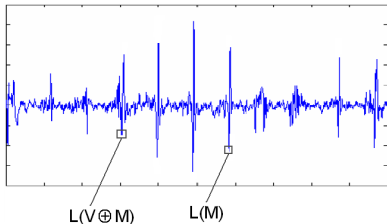
- [Chari et al. CRYPTO'99] [Goubin-Patarin. CHES'99]
- Apply secret sharing to internal variables
- A sensitive variable x is shared into $d + 1$ variables

$$x_0 \oplus x_1 \oplus \cdots \oplus x_d = x$$

- Computing on each share separately

Masking Schemes

- A lot of *first-order* masking schemes have been published
 - ▶ [Kocher et al. US Patent 1999] [Goubin-Patarin. CHES'99]
[Messerges. FSE'00] [Akkar-Giraud. CHES'01]
[Blomer et al. SAC'04] [Oswald et al. FSE'05]
[Prouff et al. CHES'06] [Prouff-Rivain. WISA'07]
- Used in current smart cards products
- Limitation: vulnerable to *second-order SCA*



Masking Schemes

- Increasing masking order
 - ⇒ increasing attack order
 - ⇒ increasing attack difficulty
- Soundness [Chari et al. CRYPTO'99]
 - ▶ Noisy leakage model: $L_i \sim x_i + \mathcal{N}(\mu, \sigma^2)$
 - ▶ Distinguishing $((L_i)_i | x = 0)$ from $((L_i)_i | x = 1)$ takes q samples:

$$q \geq cst \cdot \sigma^d$$

- Higher-order masking schemes
 - ▶ [Rivain-Prouff. CHES'10] [Kim et al. CHES'11]
[Carlet et al. FSE'12] [Coron et al. FSE'13]
- Limitation: no security proof against an adversary using the whole leakage of the computation

Physically Observable Cryptography

- [Micali-Reyzin. TCC'04]
- Framework for leaking computation
- Assumption: *Only Computation Leaks (OCL)*
- Computation divided into subcomputations $y \leftarrow C(x)$
- Each subcomputation leaks a function of its input $f(x)$

Leakage Functions

- Leakage-Resilience model [Dziembowski-Pietrzak. STOC'08]
 - ▶ bounded-range leakage functions

$$f : \{0, 1\}^n \rightarrow \{0, 1\}^\lambda \quad \text{with } \lambda \ll n$$

- Leakage model for circuits [Faust et al. EUROCRYPT'10]
 - ▶ computationally bounded leakage functions: $f \in \mathcal{AC}^0$
(computable by a circuit of constant depth)
 - ▶ noisy leakage functions: $f(x) = x \oplus \varepsilon$
with ε being some sparse error vector

Limitations

- In practice the leakage is far bigger than n bits ($\lambda \gg n$)

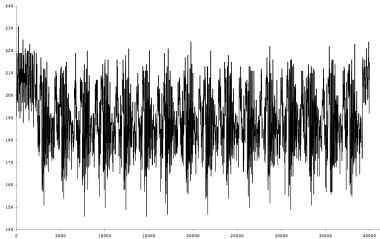
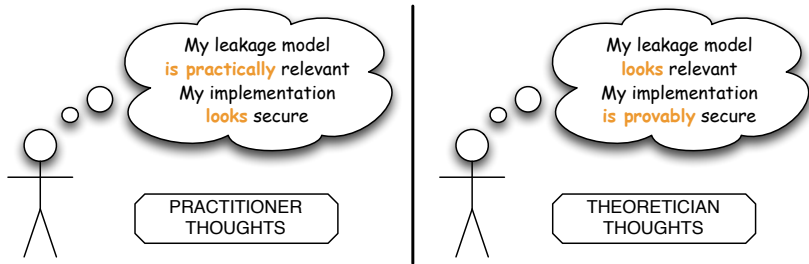


Figure: Power consumption of a DES computation.

- The leakage result from the switching activity of logic gates
 - ▶ it can hardly be modeled by an $\mathcal{AC}^0$ function
 - ▶ noise can hardly be modeled as the xor of an error vector

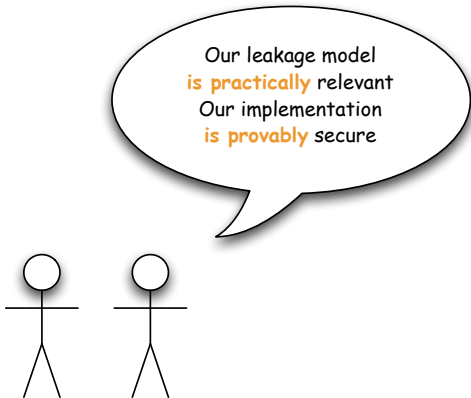
State of the Art

- Lack of practically relevant leakage models
- Masking widely used without formal proof



Our Goal

- A step toward:



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Our Contribution

- Leakage model
 - ▶ OCL assumption [Micali-Reyzin. TCC'04]
 - ▶ subcomputations = elementary calculations (a few CPU instructions, small inputs)
- New class of noisy leakage functions
 - ▶ $f(x)$ implies a *bounded bias* in the distribution of x

Our Contribution

- Formal security proof for a block cipher computation
 - ▶ negligible entropy loss on the key (w.r.t. masking order)
- Need for a *leak-free component* (for mask refreshing)

$$\underbrace{\mathbf{x} = (x_0, x_1, \dots, x_d)}_{\bigoplus_i x_i = x} \mapsto \underbrace{\mathbf{x}' = (x'_0, x'_1, \dots, x'_d)}_{\bigoplus_i x'_i = x}$$

with $(\mathbf{x} \mid x)$ and $(\mathbf{x}' \mid x)$ mutually independent.

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Notion of Bias

- Bias of X given $Y = y$:

$$\beta(X|Y = y) = \|P[X] - P[X|Y = y]\|$$

with $\|\cdot\|$ = Euclidean norm.

- Bias of X given Y :

$$\beta(X|Y) = \sum_{y \in \mathcal{Y}} P[Y = y] \beta(X|Y = y) .$$

- Related to MI by:

$$\text{MI}(X; Y) \leq \frac{N}{\ln 2} \beta(X|Y) \quad (\text{with } N = |\mathcal{X}|)$$

Model of Leaking Computation

- Every elementary calculation leaks a *noisy function* of its input
 - ▶ noise modeled by a fresh random tape argument
- f adaptively chosen by the adversary in $\mathcal{N}(1/\psi)$

$$\beta(X|f(X)) < \frac{1}{\psi}$$

- ψ is some *noise parameter*
- Capture any form of noisy leakage
- Assumption: ψ can be set by the designer (linear in the security parameter)

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Overview of the Proof

- Consider a SPN computation

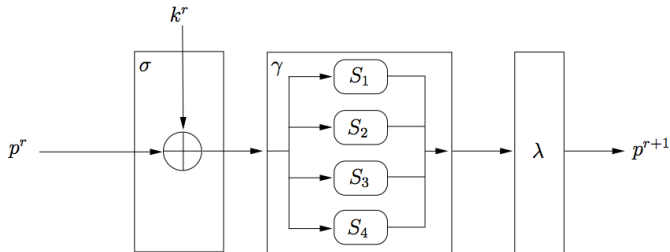


Figure: Example of SPN round.

Overview of the Proof

- Classical implementation protected with masking

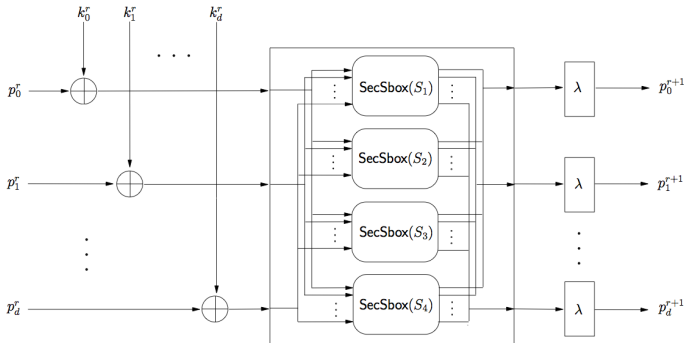


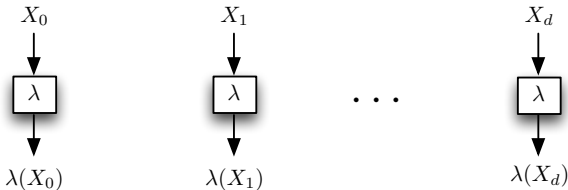
Figure: Example of SPN round protected with masking.

S-Box Computation

- [Carlet et al. FSE'12]
- Polynomial evaluation over $\text{GF}(2^n)$
- Two types of elementary calculations:
 - ▶ linear functions (additions, squares, multiplication by coefficients)
 - ▶ multiplications over $\text{GF}(2^n)$

Linear Functions

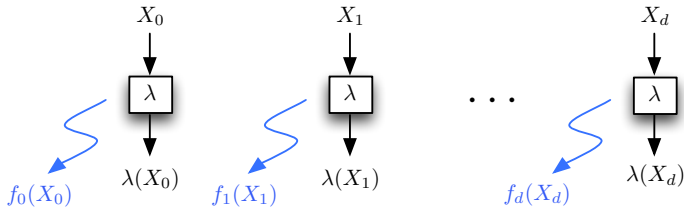
- Given a sharing $X = X_0 \oplus X_1 \oplus \dots \oplus X_d$



- Apply mask-refreshing on output sharing

Linear Functions

- Given a sharing $X = X_0 \oplus X_1 \oplus \dots \oplus X_d$



- Apply mask-refreshing on output sharing

Linear Functions

- For $f_0, f_1, \dots, f_d \in \mathcal{N}(1/\psi)$, we show

$$\beta(X | f_0(X_0), f_1(X_1), \dots, f_d(X_d)) \leq \frac{N^{\frac{d}{2}}}{\psi^{d+1}} .$$

- Taking $\psi \sim N^{\frac{1}{2}} \omega$ we get

$$\text{MI}(X; (f_0(X_0), f_1(X_1), \dots, f_d(X_d))) \leq \frac{1}{\omega^{d+1}}$$

- Result in accordance with [\[Chari et al. CRYPTO'99\]](#)

Multiplications

- Given two sharings $A = \bigoplus_i A_i$ and $B = \bigoplus_i B_i$

$$A \times B = \left(\bigoplus_i A_i\right) \left(\bigoplus_i B_i\right) = \bigoplus_{i,j} A_i B_j$$

- First step: cross-products

$$\begin{array}{cccc} A_0 \times B_0 & A_0 \times B_1 & \cdots & A_0 \times B_d \\ A_1 \times B_0 & A_1 \times B_1 & \cdots & A_1 \times B_d \\ \vdots & \vdots & \ddots & \vdots \\ A_d \times B_0 & A_d \times B_1 & \cdots & A_d \times B_d \end{array}$$

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$$\begin{array}{cccc} f_{0,0}(A_0, B_0) & f_{0,1}(A_0, B_1) & \cdots & f_{0,d}(A_0, B_d) \\ f_{1,0}(A_1, B_0) & f_{1,1}(A_1, B_1) & \cdots & f_{1,d}(A_1, B_d) \\ \vdots & \vdots & \ddots & \vdots \\ f_{d,0}(A_d, B_0) & f_{d,1}(A_d, B_1) & \cdots & f_{d,d}(A_d, B_d) \end{array}$$

Multiplications

- We have $A = g(X)$ and $B = h(X)$ where $X = \text{s-box input}$
- Bias given cross-product leakages:

For $f_{i,j} \in \mathcal{N}(1/\psi)$ we show

$$\beta(X | (f_{i,j}(A_i, B_j))_{i,j}) \leq 2N^{\frac{3d+7}{2}} \left(\frac{\lambda_1 d + \lambda_0}{\psi} \right)^{d+1}$$

with $\lambda_1 \in [1; 2]$ and $\lambda_2 \in [1; 3]$.

- Taking $\psi \sim N^{\frac{3}{2}}(\lambda_1 d + \lambda_0)\omega$ we get

$$\text{MI}(X; (f_{i,j}(A_i, B_j))_{i,j}) \leq \frac{1}{\omega^{d+1}}$$

- The noise parameter must be roughly multiplied by d

Multiplications

- Second step: refreshing
- Apply on each column and one row of

$A_0 \times B_0$	$A_0 \times B_1$	$\cdots$	$A_0 \times B_d$
$A_1 \times B_0$	$A_1 \times B_1$	$\cdots$	$A_1 \times B_d$
$\vdots$	$\vdots$	$\ddots$	$\vdots$
$A_d \times B_0$	$A_d \times B_1$	$\cdots$	$A_d \times B_d$

- We get a fresh $(d + 1)^2$ -sharing of $A \times B$

$$\begin{array}{cccc} V_{0,0} & V_{0,1} & \cdots & V_{0,d} \\ V_{1,0} & V_{1,1} & \cdots & V_{1,d} \\ \vdots & \vdots & \ddots & \vdots \\ V_{d,0} & V_{d,1} & \cdots & V_{d,d} \end{array}$$

Multiplications

- Third step: summing rows

$$Z_i \leftarrow V_{i,0} \oplus V_{i,1} \oplus \cdots \oplus V_{i,d}$$

- Takes d elementary calculations (XORs) per row:

$$T_{i,1} \leftarrow V_{i,0} \oplus V_{i,1}$$

$$T_{i,2} \leftarrow T_{i,1} \oplus V_{i,2}$$

$$\vdots$$

$$T_{i,d} \leftarrow T_{i,d-1} \oplus V_{i,d}$$

(with $Z_i = T_{i,d}$)

- Then $(Z_0, Z_1, \dots, Z_d)$ is a sharing of $A \times B$
 - ▶ Apply mask-refreshing

Multiplications

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$$Z_i \leftarrow V_{i,0} \oplus V_{i,1} \oplus \cdots \oplus V_{i,d}$$

- Takes d elementary calculations (XORs) per row:

$$\begin{array}{ll} T_{i,1} \leftarrow V_{i,0} \oplus V_{i,1} & \text{---} \\ T_{i,2} \leftarrow T_{i,1} \oplus V_{i,2} & \text{---} f_{i,1}(V_{i,0}, V_{i,1}) \\ \vdots & \text{---} f_{i,2}(T_{i,1}, V_{i,2}) \\ T_{i,d} \leftarrow T_{i,d-1} \oplus V_{i,d} & \text{---} f_{i,d}(T_{i,d-1}, V_{i,d}) \end{array}$$

(with $Z_i = T_{i,d}$)

- Then $(Z_0, Z_1, \dots, Z_d)$ is a sharing of $A \times B$
 - Apply mask-refreshing

Multiplications

- For $f_{i,j} \in \mathcal{N}(1/\psi)$ we show

$$\beta(X|F_0(Z_0), F_1(Z_1), \dots, F_d(Z_d)) \leq N^{\frac{3d+5}{2}} \left(\frac{2}{\psi}\right)^{d+1}$$

where $F_i(Z_i) = (f_{i,1}(V_{i,0}, V_{i,1}), f_{i,2}(T_{i,1}, V_{i,2}), \dots, f_{i,d}(T_{i,d-1}, V_{i,d}))$

- Taking $\psi \sim 2N^{\frac{3}{2}}\omega$ we get

$$\text{MI}(X; (F_0(Z_0), F_1(Z_1), \dots, F_d(Z_d))) \leq \frac{1}{\omega^{d+1}}$$

Putting everything together

- Several subsequences of elementary calculations
- Each provides some leakage L_t about $X_t = g_t(M, K)$
- L_t are mutually independent given (M, K)

$$\text{MI}((M, K); (L_1, L_2, \dots, L_T)) \leq \sum_{t=1}^T \text{MI}(X_t; L_t) \leq \frac{T}{\omega^{d+1}}$$

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Conclusion and Perspectives

Conclusion:

- New practically relevant leakage model
- Formal security for masking against SCA

Perspectives and open issues:

- Practical estimation of the noise parameter ψ
- Relax proof assumptions:
 - ▶ fixed noise parameter
 - ▶ no leak-free component

Conclusion and Perspectives

- What about efficiency?

